

# ALIGNING METHOD AND ALIGNING APPARATUS FOR RANDOM WORK

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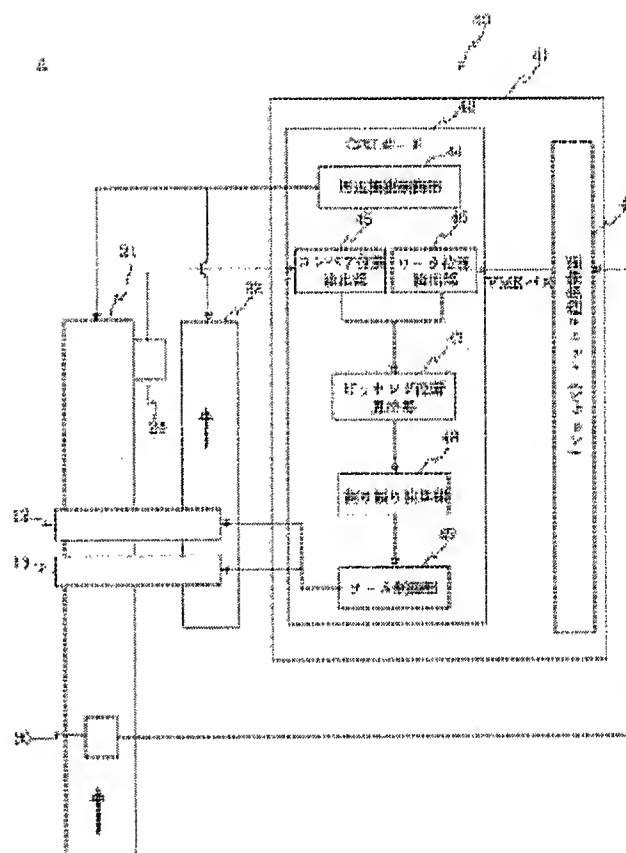
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## Abstract of JP 2002037441 (A)

**PROBLEM TO BE SOLVED:** To provide an aligning method and aligning apparatus for a random work improved in the case of aligning various works conveyed at random by a robot and carrying out the same to the next process. **SOLUTION:** In aligning works W conveyed at random by the robot and carrying out the same, one robot 10 controlled by one robot controller 40 is provided with plural arms 12, 13, and each arm 12 (13) is controlled independently of the other arm 13 (12) by the robot controller 40 to transfer the work W from the conveyance position to the carry-out position.



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